

# Low-Cost Diagnostics

Mohit Jain Microsoft Research India

#### Access to Health

Skewed Doctor-to-Patient ratio Unskilled healthcare workers Long waiting Transportation Loss of income

# Vision

To develop low-cost smartphonebased diagnostic tools

with AI assistant

to enable CHWs, teachers, primary clinicians, etc.

to perform preliminary screening with minimal training.









Collaborators: Sankara Eye Hospital, WeltHungerHilfe

# **Dry Eye Detection**

Collaborator: Sankara Eye Hospital



### **Refractive Error Estimation**

Collaborator: Sankara Eye Hospital



# Estimation: Lung Disease, Height, and BP

Collaborator: WHH





# SmartKC Past, Present, Future

Mohit Jain, Nipun Kwatra RF: Siddhartha Gairola (past), Vaibhav Ganatra (present) In collaboration with doctors at **Sankara Eye Hospital** <u>Microsoft Research India</u>



# **Smartphone-based Corneal** Topographer for Keratoconus Diagnosis

Mohit Jain, Nipun Kwatra RF: Siddhartha Gairola (past), Vaibhav Ganatra (present) In collaboration with doctors at **Sankara Eye Hospital** <u>Microsoft Research India</u>

### **Keratoconus Disease**

Distorts cornea into a cone-like shape Impact teens Causes (partial) blindness

Affects 2.3% people in India

Treatment:

- $\rightarrow$  Contact lenses
- $\rightarrow$  Corneal cross-linking
- $\rightarrow$  Corneal transplant



Early Diagnosis is the Key!

# Diagnostics: Placido Disc

Mires



Cheap | Doctor needed | Low accuracy

# **Diagnostics: Corneal Topographers**



Optikon Keratron

Medmont E 300

Zeiss Atlas 9000

NIDEK Scan III

Expensive No doctor needed High accuracy



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Curvature (Axial and Tangential) Map, sim-K1 (steepest), sim-K2



#### Goal

#### To develop a **low-cost portable** corneal topographer, which **captures the mire image** and **outputs curvature maps**.









# I. Placido Disc



### **.** Placido Disc









#### Weighs: 140 grams | Costs: Rs 2500 (\$33)

![](_page_16_Picture_1.jpeg)

![](_page_17_Picture_0.jpeg)

![](_page_18_Picture_0.jpeg)

# **Real-time on-device Image Processing**

Al assisted app

#### Real-time Checks:

- Exposure
- Sharpness

Center alignment Auto-capture

![](_page_19_Picture_6.jpeg)

![](_page_20_Picture_0.jpeg)

# II. Heatmap Generation: Image Processing

![](_page_21_Picture_1.jpeg)

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![](_page_22_Picture_0.jpeg)

# **Working Distance Computation**

![](_page_23_Figure_1.jpeg)

Working distance =  $gap_{base}$  + placido\_length +  $gap_{top}$ 

Two eye properties:

- the radius of the human cornea is similar (7.79±0.27mm),
- the shape of the cornea is distorted mainly in the central region

For a given gap<sub>top</sub>, the radius of the mire reflections in the outer region is same across patients.

Simulation environment followed by a simple regression model to learn mapping between gap<sub>top</sub> and radius of the outer mire.

### **Data and Evaluation**

57 patients (35 female, 22 male), age=23.7±7.6 years

#### 101 eyes [67 non-keratoconus and 34 keratoconus]

#### 4 doctors rating: non-keratoconus, keratoconus, retake

![](_page_24_Picture_4.jpeg)

![](_page_25_Figure_0.jpeg)

### Results

	Device	Sensitivity	Specificity
	Keratron	100.0%	65.8%
Doctor I	SmartKC	93.5%	95.9%
	Keratron	100.0%	93.3%
Doctor 2	SmartKC	92.3%	100.0%
Doctor 3	Keratron	94.1%	52.6%
	SmartKC	93.7%	100.0%
	Keratron	100.0%	53.8%
Doctor 4	SmartKC	94.1%	100.0%
Overall	Keratron	100.0%	64.5%
	SmartKC	<mark>94.1%</mark>	<mark>100.0%</mark>

#### Sensitivity: **92.3 - 94.1%**

To correctly identify people **with** Keratoconus. Sensitivity = TP/(TP+FN)

#### Specificity: **95.9% - 100.0%**

Test to correctly identify people **without** Keratoconus. Specificity = TN/(TN+FP)

### What Next?

![](_page_27_Figure_1.jpeg)

### What Next?

![](_page_28_Figure_1.jpeg)

# **Universities and Orgs Reached**

**Research Orgs** 

![](_page_29_Figure_2.jpeg)

#### Ophthalmologist

<u>Manufacturers</u> Device

#### CELA

Thought Leader

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azure_function/file_uploader Merge branch 'main' of https://github.com/microsoft,		com/microsoft/Smart	
🖿 data	Updating sample images and their hea	tmap results	
enhance_img	deleting .pyc files		

#### Disclaimer

The software and hardware described in this repository is provided for research and development use only. The software and hardware are not intended for use in clinical decision-making or for any other clinical use, and their performance for clinical use has not been established. You bear sole responsibility for any use of this software and hardware, including incorporation into any product intended for clinical use.

# InstaKC by Remidio

![](_page_31_Picture_1.jpeg)

![](_page_31_Picture_2.jpeg)

![](_page_31_Picture_3.jpeg)

### What Next?

![](_page_33_Figure_1.jpeg)

based Corneal Topographers

# Limitations

- Curvature underestimation in severe cases: Improper mire segmentation
- 2. Curvature overestimation in normal/mild cases: **Incorrect mire localization** due to missing mire segments
- 3. Errors compounded in 3D reconstruction (Arc-Step)

#### Gold Standard

![](_page_34_Picture_5.jpeg)

![](_page_34_Picture_6.jpeg)

#### Errors in Mire Localization

![](_page_34_Picture_8.jpeg)

#### Faulty 3D reconstruction

![](_page_34_Picture_10.jpeg)

#### Faulty Axial Heatmap

![](_page_34_Picture_12.jpeg)

# Solution 1

#### **U-Net based Mire Segmentation**

**Existing**: Image-processing based fingerprint-detection algo.

**Limitation**: Assumed mires to be circular, leading to underestimation in severe cases.

**Solution**: Trained a U-Net for mire segmentation.

- Combined data augmentation and pseudolabels from existing algorithm for training
- Manually filtered out erroneous cases for training (shown)

![](_page_35_Picture_7.jpeg)

# Solution 2

#### **Graph based Mire Localization**

**Existing**: Radial Scanning algorithm.

**Limitation**: Assumed mires to be complete – did not account for broken mire segments. This led to mire shifts and artifacts in the heatmaps.

**Solution**: Use spatial information from the neighbourhood to identify broken mire segments and correct mire shifts.

![](_page_36_Picture_5.jpeg)

# Solution 3

#### **Robust 3D Reconstruction**

Existing: Arc-Step

**Limitation**: Assumed mires to be complete – not compatible with broken mire segments; requires interpolation in 2D space.

**Solution**: Enable compatibility with broken mires to allow interpolation in 3D space

![](_page_37_Picture_5.jpeg)

![](_page_37_Figure_6.jpeg)

### Results

![](_page_38_Figure_1.jpeg)

### **Results: Sim-K and Keratoconus**

		Sim-K1			Sim-K2		
		MAE	MAPE	Corr.	MAE	MAPE	Corr.
Success Set	SmartKC	1.29	2.64	0.89	2.25	4.82	0.066
	SmartKC++	1.33	2.72	0.92	1.38	3.04	0.78
Failure Set	SmartKC	4.22	7.49	0.62	8.22	16.15	-0.25
	SmartKC++	1.78	3.03	0.925	2.01	3.94	0.928

SmartKC++ exhibits similar performance on both success and failure sets

Device	KT Condition	Acc.	Sens.	Spec.	Prec.	Recall	<b>F1</b>
Keratron	K1 >46.995 or (K1 - K2) >1.523	80.37	85.71	70.27	84.51	85.71	85.11
SmartKC	K1 >44.35 or K1-K2 >2.644	81.32	87.27	72.22	82.76	87.27	84.96
SmartKC++		89.01	87.27	91.67	94.12	87.27	90.57

SmartKC++ **outperforms** SmartKC on Automated Keratoconus Detection

### What Next?

![](_page_40_Figure_1.jpeg)

#### Tear Breakup Time

![](_page_41_Picture_1.jpeg)

# Break Types

![](_page_42_Figure_1.jpeg)

Line Break

Merge Break

Out-of-shape Break

Distortion Break

# **Video Processing Pipeline**

![](_page_43_Figure_1.jpeg)

### Results

#### Comparison with medical devices

Device	<b>Threshold</b> (s)	Sensitivity (%)	Specificity (%)
Tomey RT-7000 Keratometer	5	82	60
IDRA Plus	7.75	89	69
Oculus Keratograph 5M	6.69	80	67.59
<b>DEDector</b> – Auto (ours)	10	77.78	78.57

#### Comparison with other screening tools

Method	Phone	<b>Eval Set Size</b>	Acc.	Sens.	Spec.
DryEyeRhythm	Yes	82 (42 DED)	71.95	50.00	95.00
DEvice©(AI, Rome, Italy)	No	40 (20 DED)	77.50	60.00	95.00
<b>DEDector</b> - Manual (ours)	Yes	46 (18 DED)	80.43	77.78	82.14
DEDector - Auto (ours)	Yes	46 (18 DED)	78.26	77.78	78.57

### What Next?

![](_page_45_Figure_1.jpeg)

# Keratoconus: Corneal Tomographer

![](_page_46_Picture_1.jpeg)

![](_page_46_Picture_2.jpeg)

- Keratoconus manifests on the posterior corneal surface
- Corneal Tomographer captures individual cross-sections
  of the cornea
  - $\rightarrow$  Consolidate information for 3D reconstruction
  - → Generate Pachymetry map

![](_page_46_Picture_7.jpeg)

#### **Pentacam Report**

![](_page_47_Figure_1.jpeg)

# Scheimpflug Principle

*are using.* If you the the depth of field will be to infinity. ↓ For annera has a hyperfe

![](_page_48_Picture_2.jpeg)

![](_page_48_Picture_3.jpeg)

# Our Approach

- Involves a tilt between three planes:
  - Object, Lens, and Image.
- To focus on a tilted object w.r.t the lens plane

![](_page_49_Picture_4.jpeg)

![](_page_49_Picture_5.jpeg)

![](_page_49_Picture_6.jpeg)

# Conclusion

- Diagnostics device research is complex, takes time
- But its highly rewarding and impactful!
- Interdisciplinary collaboration is critical for success
- One research thread often branches into multiple new research opportunities
- Real-world deployments provide valuable insights

### Thank You!

Mohit Jain mohja@microsoft.com Microsoft Research India